

Let  $V$  be a vector space over  $\mathbb{R}$  (or  $\mathbb{C}$ ) such that  $\dim(V) = n < \infty$ . Let  $T : V \rightarrow V$  be a linear transformation (since we are mapping from  $V$  to itself, we could refer to  $T$  as a linear operator).

**Definition:** Let  $\mathbf{v} \in V$  such that  $\mathbf{v} \neq \mathbf{0}$  and  $T(\mathbf{v}) = \lambda\mathbf{v}$ . Then  $\mathbf{v}$  is an *eigenvector* for  $T$  with *eigenvalue*  $\lambda$ . Moreover, we say that  $\lambda \in \mathbb{R}$  (or  $\mathbb{C}$ ) is an *eigenvalue* for  $T$  if  $T$  has an eigenvector with eigenvalue  $\lambda$ .

*Note:* While 0 can be an eigenvalue,  $\mathbf{0}$  is not allowed to be an eigenvector. Otherwise, since  $T(\mathbf{0}) = \mathbf{0} = \lambda\mathbf{0}$ , we would have that every scalar is an eigenvalue of  $T$  and  $\mathbf{0}$  would have every scalar as its eigenvalue!

**Definition:** Let  $f(t) = \det(T - tI)$ . Then  $f(t)$  is called the *characteristic polynomial* of  $T$ .<sup>1</sup>

*Note:*  $\lambda$  is an eigenvalue of  $T \Leftrightarrow$  there exists a non-zero vector  $\mathbf{v}$  such that  $T(\mathbf{v}) = \lambda\mathbf{v} \Leftrightarrow$  there exists a non-zero vector  $\mathbf{v}$  such that  $(T - \lambda I)(\mathbf{v}) = \mathbf{0} \Leftrightarrow \text{Ker}(T - \lambda I) \neq \{\mathbf{0}\} \Leftrightarrow T - \lambda I$  is not 1-1  $\Leftrightarrow T - \lambda I$  is not invertible  $\Leftrightarrow \det(T - \lambda I) \neq 0$ . We have just proved...

**Theorem:**  $\lambda$  is an eigenvalue of  $T$  if and only if  $\lambda$  is a root of the characteristic polynomial of  $T$  (that is  $f(\lambda) = \det(T - \lambda I) = 0$ ).

**Facts:** Let  $f(t)$  be the characteristic polynomial of  $T$ . Then  $f(t)$  is a polynomial of degree  $n$  whose leading coefficient is  $(-1)^n$ . In addition,  $f(0) = \det(T)$  (the constant term is just the determinant of  $T$ ). Also, the coefficient of  $t^{n-1}$  in  $f(t)$  is  $(-1)^{n-1}\text{tr}(T)$  (i.e.,  $\pm$  the trace of  $T$ ).

**Definition:** Factor  $T$ 's characteristic polynomial (over  $\mathbb{C}$ ):  $f(t) = (-1)^n(t - \lambda_1)^{m_1}(t - \lambda_2)^{m_2} \cdots (t - \lambda_k)^{m_k}$  (where  $\lambda_i \neq \lambda_j$  for  $i \neq j$  and  $m_i > 0$ ). Then the roots of  $f(t)$  (i.e. the eigenvalues of  $T$ ) are  $\lambda_1, \dots, \lambda_k$ . We say that the *algebraic multiplicity* of  $\lambda_i$  is  $m_i$  (the number of factors  $(t - \lambda_i)$  appearing in the characteristic polynomial). Notice that the sum of the algebraic multiplicities is  $n = \dim(V)$  (the degree of the characteristic polynomial).

*Technical note:* More accurately, if we are working over  $\mathbb{R}$ , the non-real roots are not actually eigenvalues.

**Definition:** Let  $E_\lambda = \text{Ker}(T - \lambda I) = \{\mathbf{v} \in V \mid (T - \lambda I)(\mathbf{v}) = \mathbf{0}\} = \{\mathbf{v} \in V \mid T(\mathbf{v}) = \lambda\mathbf{v}\} = \{\mathbf{0}\} \cup \{\mathbf{v} \in V \mid \mathbf{v} \text{ is an eigenvector of } T \text{ with eigenvalue } \lambda\}$ . If  $E_\lambda \neq \{\mathbf{0}\}$  (i.e.,  $\lambda$  is an eigenvalue), then we call  $E_\lambda$  an *eigenspace* of  $T$ . Notice that  $E_\lambda$  is a subspace of  $V$  (since it is the kernel of a linear transformation).

**Definition:**  $\dim(E_\lambda) = \dim(\text{Ker}(T - \lambda I)) = \text{nullity}(T - \lambda I)$  is called the *geometric multiplicity* of  $\lambda$ . This is the number of linearly independent eigenvectors with eigenvalue  $\lambda$ . Notice that if  $\lambda$  is an eigenvalue then  $E_\lambda$  cannot be the zero subspace. Thus geometric multiplicities of eigenvalues are always at least 1.

**Theorem:** Let  $\lambda$  be an eigenvalue of  $T$  with algebraic mult.  $m$  and geometric mult.  $g$ . Then  $1 \leq g \leq m$ .

**Theorem:** Eigenvectors with different eigenvalues are linearly independent. Moreover, if  $S_i$  is a linearly independent set of eigenvectors with eigenvalue  $\lambda_i$  and  $\lambda_i \neq \lambda_j$  for  $i \neq j$ , then  $S_1 \dot{\cup} S_2 \dot{\cup} \cdots \dot{\cup} S_k$  is a linearly independent set.

**Definition:**  $T$  is *diagonalizable* if there is a basis for  $V$  consisting of eigenvectors for  $T$ . Notice if  $\beta$  is such a basis, then  $[T]_\beta$  is a diagonal matrix!

**Corollary:**  $T$  is diagonalizable (over  $\mathbb{R}$ ) if and only if the eigenvalues of  $T$  all belong to  $\mathbb{R}$  (i.e. the characteristic polynomial completely factors over  $\mathbb{R}$ ) and the geometric and algebraic multiplicities of each eigenvalue match.

<sup>1</sup>This is the definition in Lay. Other texts define  $g(t) = \det(tI - T)$  to be the characteristic polynomial. Notice that  $f(t) = (-1)^n g(t)$  where  $n = \dim(V)$ . So for even sized matrices  $f = g$  and for odd sized matrices  $f = -g$ .