

Some Plots to supplement our discussion of...

Conformal Mappings

Also, a construction (and plots related to)...

Linear Fractional Transformations

(i.e. Möbius Transformations)

```
> restart;
with(LinearAlgebra):
with(plots):

assume(x,'real',y,'real',t,'real');
```

Our conformal map (note that $g'(z) = 2z$ so this is not conformal at $z=0$)...

```
> g := z -> z^2:
'g(z)' = g(z);

$$g(z) = z^2 \quad (1)$$

```

This is a parameterization of the circle: $(x - 1)^2 + y^2 = 1$ (i.e. radius 1 centered at (1,0)).

We have that $0 = tA \leq t \leq tB = 2\pi$.

B1 plots the circle before $g(z)$ is applied (i.e. in the domain) and A1 plots the image of the circle under the mapping $g(z)$ (i.e. in the codomain).

```
> xp := t -> cos(t)+1:
yp := t -> sin(t):
tA := 0: tB := 2*Pi:

'r(t)' = [xp(t),yp(t)];

B1 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=red):
A1 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=
constrained, color=red):


$$r(t) = [\cos(t) + 1, \sin(t)] \quad (2)$$

```

This parameterizes a line segment with $x = 1$ and $y = t$ for $-2 \leq t \leq 2$.

B2 and A2 are then plots before and after $g(z)$ is applied.

```
> xp := t -> 1:
yp := t -> t:
tA := -2: tB := 2:
```

```

'r(t)' = [xp(t),yp(t)];

B2 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=green):
A2 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=
constrained, color=green):
 $r(t) = [1, t]$  (3)

```

This parameterizes a line segment with $x = 2t$ and $y = -t - 1$ for $-1 \leq t \leq 1$.

Again, B3 and A3 are the before and after plots.

```

> xp := t -> 2*t:
  yp := t -> -1-t:
  tA := -1:  tB := 1:

'r(t)' = [xp(t),yp(t)];

B3 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=blue):
A3 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=
constrained, color=blue):
 $r(t) = [2t, -1 - t]$  (4)

```

These commands display the before plots together (in the domain of $g(z)$) and the after plots together (in the codomain of $g(z)$)...

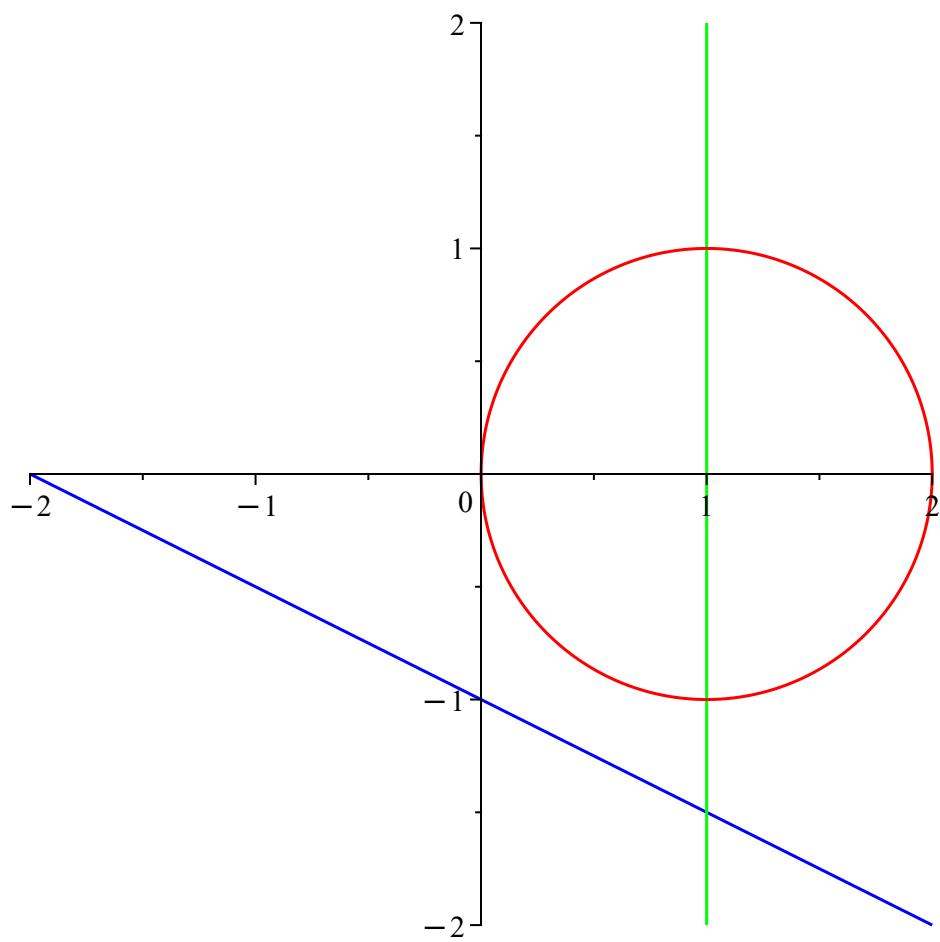
```

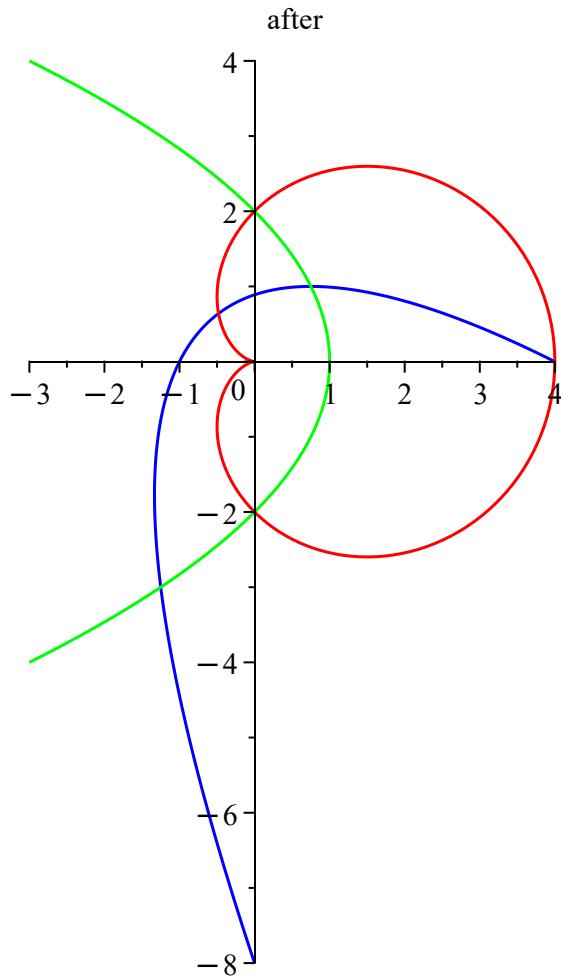
> display({B1,B2,B3},scaling=constrained,title="before");

display({A1,A2,A3},scaling=constrained,title="after");

```

before





Linear Fractional Transformations

This code associates a linear fractional transformation with a 2x2 matrix A...

```
> f := (A, z) -> (A[1,1]*z+A[1,2]) / (A[2,1]*z+A[2,2]):  
'f_A(z)' = f(A, z);
```

$$f_A(z) = \frac{A_{1,1}z + A_{1,2}}{A_{2,1}z + A_{2,2}} \quad (5)$$

This is code to automate the "existence" proof creating a linear fractional transformation sending z_0, z_1, z_2 to w_0, w_1, w_2 .

`matrixToLFT(A)` outputs a function (= linear fractional transformation) associated with a 2x2 matrix A.

`ptsToMatrix(z1,z2,z3)` creates a matrix which is associated with a linear fractional transformation which sends z_1, z_2, z_3 to $0, 1, \infty$.

`ptsTopts(z1,z2,z3,w1,w2,w3)` creates function (= linear fractional transformation) which sends z_1, z_2, z_3 to w_1, w_2, w_3 .

Note: ∞ is an allowed value of for a z or w point. On the other hand, this code does not check that the user supplied distinct points.

```
> matrixToLFT := proc(A)  
    return z -> simplify((A[1,1]*z+A[1,2]) / (A[2,1]*z+A[2,2]));
```

```

end proc:

ptsToMatrix := proc(z1,z2,z3)
  if z1=z2 or z1=z3 or z2=z3 then return "Use Distinct Points"; end if;

  if z1=infinity then
    return <<0,1>|<z2-z3,-z3>>;
  end if;

  if z2=infinity then
    return <<1,1>|<-z1,-z3>>;
  end if;

  if z3=infinity then
    return <<1,0>|<-z1,z2-z1>>;
  end if;

  return <<z2-z3,z2-z1>|<-z1*(z2-z3),-z3*(z2-z1)>>;
end proc:

ptsToPts := proc(z1,z2,z3,w1,w2,w3)
local A,B;

A := ptsToMatrix(z1,z2,z3);
B := ptsToMatrix(w1,w2,w3);

return matrixToLFT(B^(-1).A);
end proc:

```

Example: Create a map $g(z)$ which sends $1,i,\infty$ to $0,-1,i$

Maple can verify that 1 maps to 0 and i maps to -1 (it has trouble with ∞ although the formula is actually correct).

```

> g:= ptsToPts(1,I,infinity,0,-1,I):
'g(z)' = g(z);

$$g(z) = \frac{-I(1-z)}{1+z} \quad (6)$$

> g(1),g(I),g(infinity);
0, -1, undefined + undefinedI \quad (7)

```

This code replicates what was done for the conformal map above. Now we apply our linear fractional transformation.

```

> xp := t -> cos(t)+1:
yp := t -> sin(t):
tA := 0: tB := 2*Pi:

'r(t)' = [xp(t),yp(t)];

B1 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=red):

```

```

A1 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=constrained, color=red):

$$r(t) = [\cos(t\sim) + 1, \sin(t\sim)] \quad (8)$$


> xp := t -> 1:
yp := t -> t:
tA := -2: tB := 2:

'r(t)' = [xp(t),yp(t)];

B2 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=green):
A2 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=constrained, color=green):

$$r(t) = [1, t\sim] \quad (9)$$


> xp := t -> 2*t:
yp := t -> -1-t:
tA := -1: tB := 1:

'r(t)' = [xp(t),yp(t)];

B3 := plot([xp(t),yp(t), t=tA..tB], scaling=constrained, color=blue):
A3 := plot([Re(g(xp(t)+I*yp(t))), Im(g(xp(t)+I*yp(t))), t=tA..tB], scaling=constrained, color=blue):

$$r(t) = [2t\sim, -1 - t\sim] \quad (10)$$

```

Notice that the circle and lines transform to circles (since only line segments are plotted in the domain, only arc of circles show up in the codomain).

Also, 1 and i are plotted with a circle and asterisk in the domain. Their images 0 and -1 are plotted with the same symbols in the codomain as well as the image of ∞ (which is "i" and is plotted with a diamond).

```

> display({B1,B2,B3,
            pointplot([[1,0]],color=black,symbol=circle,symbolsize=30),
            pointplot([[0,1]],color=black,symbol=asterisk,symbolsize=30)}, scaling=constrained,title="before");

display({A1,A2,A3,
            pointplot([[0,0]],color=black,symbol=circle,symbolsize=30),
            pointplot([[-1,0]],color=black,symbol=asterisk,symbolsize=30),
            pointplot([[0,1]],color=black,symbol=diamond,symbolsize=30)}, scaling=constrained,title="after");
```

before

