Math 4010-101

Homework #5

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#1. Invariant, Cyclic, Minimal I'll go over some background. This may look intimidating, but the problems below are actually pretty straightforward.

Let $T: V \to V$ be a linear operator on a finite dimensional vector spaces over some field \mathbb{F} . Let $f(t) = a_n t^n + \cdots + a_1 t + a_0$ be a polynomial with coefficients in \mathbb{F} (i.e., $f(t) \in \mathbb{F}[t]$). Recall that $f(T): V \to V$ is a linear operator where $f(T)(\mathbf{v}) = a_n T^n(\mathbf{v}) + \cdots + a_1 T(\mathbf{v}) + a_0 \mathbf{v}$ for all $\mathbf{v} \in V$ and $T^k(\mathbf{v}) = \underbrace{T(T(\cdots T(\mathbf{v}) \cdots))}_{k-\text{times}}$.

There is a monic (i.e., leading coefficient is 1) polynomial, m(t), such that m(T) = 0 (the zero operator: $(m(T))(\mathbf{v}) = \mathbf{0}$ for all $\mathbf{v} \in V$) and given any other polynomial g(t) such that g(T) = 0, we have that g(t) is a multiple of m(t). This polynomial is called the *minimal polynomial* of T.

Note: One can show that the set of all polynomials g(t) that annihilate T (i.e., g(T) = 0) form something an *ideal* in the polynomial ring $\mathbb{F}[t]$. It turns out (since $\mathbb{F}[t]$ is a principal ideal domain) that this ideal has a generator. In fact, it has a *unique* monic (= leading coefficient is 1) generator. This unique monic generator is nothing more than our minimal polynomial.

Let W be a subspace of V. We say W is T-invariant if $T(\mathbf{w}) \in W$ for all $\mathbf{w} \in W$ (i.e., $T(W) \subseteq W$).

If W is T-invariant, we can restrict T's domain to W and since $T(W) \subseteq W$, we can also cut its codomain down to W. Thus we get a map $S = T \Big|_{W} : W \to W$. In other words, S is a linear operator on W (instead of V) and it matches T on its domain (i.e., $S(\mathbf{w}) = T(\mathbf{w})$ for all $\mathbf{w} \in W$).

- (a) Suppose W is T-invariant. Show that W is also f(T)-invariant.
- (b) Let $\mathbf{v} \in V$ and let $W = \operatorname{span}\{\mathbf{v}, T(\mathbf{v}), T^2(\mathbf{v}), \ldots\}$ (i.e., W is the T-cyclic subspace generated by \mathbf{v}). Obviously W is a subspace because it is defined as a span. Show that W is T-invariant.
- (c) Again, let $W = \operatorname{span}\{\mathbf{v}, T(\mathbf{v}), T^2(\mathbf{v}), \dots\}$. Suppose that $T\Big|_W = S$ (the restriction of T to W) has a minimal polynomial $m(t) = t^3 2t + 5$. Prove that $\alpha = \{\mathbf{v}, T(\mathbf{v}), T^2(\mathbf{v})\}$ is a basis for W and find $[S]_{\alpha}$. *Hint:* Showing α is a basis elements of W are of the form $g(T)(\mathbf{v})$ for some polynomial g(t). Consider dividing g(t) by m(t): there exist unique polynomials q(t) and r(t) such that g(t) = q(t)m(t) + r(t) where either r(t) = 0 or the degree of r(t) is less than the degree of m(t).

Note: $[S]_{\alpha}$ is an example of something called a *companion matrix*. Companion matrices are the building blocks for rational canonical form.

#2. Eigenproblem Let $T: V \to V$ be a linear operator on a finite dimensional vector spaces over some field \mathbb{F} .

- (a) Explain why $\lambda = 0$ is an eigenvalue if and only if T is not invertible. Then suppose T is invertible and show that if λ is an eigenvalue of T, then λ^{-1} is an eigenvalue of T^{-1} .
- (b) **[Extra credit:]** Recall that $T^*: V^* \to V^*$ is the transpose map defined by $T^*(f) = f \circ T$. Show that T and T^* have the same eigenvalues.
- #3. Jordan Forms If A is a 2 × 2 matrix (working over an algebraically closed field like the complex numbers), then A must either have one or two distinct eigenvalues. The possible Jordan forms of A look like: $J_1 = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$, $J_2 = \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix}$, or $J_3 = \begin{bmatrix} \lambda & 0 \\ 0 & \mu \end{bmatrix}$. These go with characteristic polynomials $f_1(t) = (t - \lambda)^2$, $f_2(t) = (t - \lambda)^2$, and $f_3t(t) = (t - \lambda)(t - \mu)$ and minimal polynomials $m_1(t) = t - \lambda$, $m_2(t) = (t - \lambda)^2$, and $m_3(t) = (t - \lambda)(t - \mu)$. The first and third are diagonalizable while the second is not.
 - (a) Suppose λ , μ , and η are 3 distinct scalars. If A is 3×3 it can have eigenvalues: λ , μ , and η (all distinct); λ , μ with λ repeated twice; OR just λ repeated 3 times.

Write down all possible 3×3 Jordan forms (up to reorganizing). State each form's characteristic and minimal polynomial and whether the corresponding matrix is diagonalizable.

(b) A square matrix A is *nilpotent* if $A^k = 0$ for some positive exponent k > 0. Suppose A is diagonalizable, show that A = 0.

Hint: Eigenvalues of nilpotents are? Minimal polynomial of a diagonalizable matrix?

- (c) We have a matrix B whose eigenvalues are 1 and 2. Moreover: $\dim(\ker(B-I)) = 2$, $\dim(\ker(B-I)^2) = 3$, $\dim(\ker(B-I)^3) = 3$; $\dim(\ker(B-2I)) = 2$, $\dim(\ker(B-2I)^2) = 4$, $\dim(\ker(B-2I)^3) = 4$. Write down the Jordan form of B along with B's characteristic and minimal polynomials. Is B diagonalizable? Is B invertible? What is $\det(B)$? What is $\operatorname{trace}(B)$?
- **#4. Computational Difficulties** You probably should do these computations in Maple (or similar software). Feel free to submit a Maple file (or pdf print of such).

(a) Let
$$A = \begin{bmatrix} 2 & -1 & -1 & -1 & 0 & -1/2 & -1 \\ 2 & 4 & -1 & 3 & -1 & -1/2 & -1 \\ -6 & -4 & 5 & -5 & 1 & 1 & 3 \\ -4 & -3 & 3 & -3 & 2 & 2 & 3 \\ -6 & -4 & 3 & -5 & 3 & 3/2 & 3 \\ 0 & 0 & 0 & 0 & 0 & 2 & 0 \\ 8 & 5 & -5 & 7 & -2 & -5/2 & -3 \end{bmatrix}$$
.
Copy/paste into Maple:
with(LinearAlgebra):
 $A := \langle \langle 2, 2, -6, -4, -6, 0, 8 \rangle | \langle -1, 4, -4, -3, -4, 0, 5 \rangle | \langle -1, -1, 5, 3, 3, 0, -5 \rangle | \langle -1, 3, -5, -3, -5, 0, 7 \rangle | \langle 0, -1, 1, 2, 3, 0, -2 \rangle | \langle -1/2, -1/2, 1, 2, 3/2, 2, -5/2 \rangle | \langle -1, -1, 3, 3, 3, 0, -3 \rangle \rangle;$

Find the Jordan form of A as well as an invertible matrix P (i.e., a *transition matrix*) such that $P^{-1}AP$ is the Jordan form of A. You may use Maple to do your computations, but I want to see your work building up a basis of generalized eigenvectors (i.e. don't just use the "JordanForm" command).

(b) Let
$$B = \begin{bmatrix} -17 & -9 & -3 \\ 36 & 19 & 6 \\ 18 & 9 & 4 \end{bmatrix}$$
.
Copy/paste into Maple:
B := <<-17,36,18>|<-9,19,9>|<-3,6,4>>;

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As before, find the Jordan form and a corresponding transition matrix for B (show your work). Then use these matrices to find \sqrt{B} (i.e., $(\sqrt{B})^2 = B$) and e^B . [Extra credit: Find $\cos(B)$.]