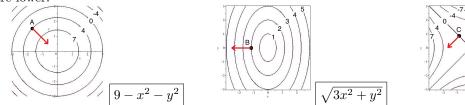
Name: ANSWER KEY

Be sure to show your work!

1. (12 points) Three level curve plots are shown below. I have labeled the levels so you know which curves are higher and which are lower.



- (a) The plots above correspond to the functions: $f(x,y) = x^2 y^2$, $f(x,y) = 9 x^2 y^2$, and $f(x,y) = \sqrt{3x^2 + y^2}$. Write the correct formula below each plot.
- (b) Sketch a gradient vector at the points A, B, and C. If the vector is **0**, draw an "X" on the point. [Don't worry about having the correct length. I'm just looking for the correct direction.]

Notice that the level curves of $f(x,y)=x^2-y^2$ are $x^2-y^2=c$ which are hyperbolas for $c\neq 0$ and $y=\pm x$ when c=0. This is the third graph. $f(x,y)=9-x^2-y^2$ has circles $9-x^2-y^2=c$ (so $x^2+y^2=9-c$) as level curves and $f(x,y) = \sqrt{3x^2 + y^2}$ has ellipses as level curves. Also, remember that gradient vectors should be perpendicular to level curves and should point to "higher ground".

2. (10 points) Let z = f(u, v) where u = x + y and v = x - y. Show that $\left(\frac{\partial z}{\partial u}\right) \left(\frac{\partial z}{\partial u}\right) = \left(\frac{\partial z}{\partial u}\right)^2 - \left(\frac{\partial z}{\partial v}\right)^2$. $\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x} = f_u(1) + f_v(1) \qquad \qquad \frac{\partial z}{\partial u} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y} = f_u(1) + f_v(-1)$ $\frac{\partial z}{\partial x} \cdot \frac{\partial z}{\partial y} = (f_u + f_v)(f_u - f_v) = (f_u)^2 - (f_v)^2 = \left(\frac{\partial z}{\partial y}\right)^2 - \left(\frac{\partial z}{\partial y}\right)^2$

3. (8 points) Find an equation for the plane tangent to $x^2y + \sin(xyz) + xz = -2$ at the point (x, y, z) = (-1, 0, 2).

This is a level surface where $F(x, y, z) = x^2y + \sin(xyz) + xz$ and F(x, y, z) = -2. Notice that $F(-1, 0, 2) = (-1)^20 + ($ $\sin((-1)0(2)) + (-1)2 = -2$. (Which better be true if (-1,0,2) is supposed to lie on this surface!)

We have a point. We know that $\nabla F(-1,0,2)$ will give us our normal vector.

 $\nabla F = \langle 2xy + \cos(xyz)yz + z, x^2 + \cos(xyz)xz, \cos(xyz)xy + x \rangle$ $\nabla F(-1,0,2) = \langle 2(-1)0 + \cos(-1(0)2) \cdot 0(2) + 2, (-1)^2 + \cos(-1(0)2) \cdot (-1)2, \cos(-1(0)2) \cdot (-1)0 + (-1) \rangle$ $= \langle 0 + 0 + 2, 1 - 2, 0 - 1 \rangle = \langle 2, -1, -1 \rangle$ 2(x-(-1))-1(y-0)-1(z-2)=0 \implies 2x-y-z+4=0

4. (10 points) Limits

 $\lim_{(x,y)\to(0,0)} \frac{x^2 + y^2 + x^3}{x^2 + u^2}$ (a) Show the following limit **does** exist:

About our only tool for showing a limit exists is switching to polar coordinates. Let $x = r\cos(\theta)$ and $y = r\sin(\theta)$. Then

 $x^{2} + y^{2} = r^{2}. \text{ Recall that the origin has polar coordinates } (r, \theta) = (0, \theta) \text{ no matter what } \theta \text{ is.}$ $\lim_{(x,y)\to(0,0)} \frac{x^{2} + y^{2} + x^{3}}{x^{2} + y^{2}} = \lim_{(r,\theta)\to(0,\theta)} \frac{r^{2} + r^{3}\cos^{3}(\theta)}{r^{2}} = \lim_{(r,\theta)\to(0,\theta)} \frac{r^{2}(1 + r\cos^{3}(\theta))}{r^{2}} = \lim_{(r,\theta)\to(0,\theta)} 1 + r\cos^{3}(\theta) = 1 + 0 = \boxed{1}$

Notice that even though the final expression involves θ , $\cos^3(\theta)$ varies between -1 and 1 so as r goes to 0, $r\cos^3(\theta)$ must also go to 0.

 $\lim_{(x,y)\to(0,0)} \frac{xy}{x^2 + u^2}$ (b) Show the following limit **does not** exist:

If we approach along y=0, we get $\lim_{(x,0)\to(0,0)}\frac{x(0)}{x^2+0^2}=\lim_{x\to0}\frac{0}{x^2}=0$. If we approach along y=x, we get $\lim_{(x,x)\to(0,0)}\frac{x\cdot x}{x^2+x^2}=0$ $\lim_{x\to 0} \frac{x^2}{2x^2} = \frac{1}{2}$. Since $0 \neq \frac{1}{2}$, we can conclude that this limit does not exist.

5. (10 points) Let $z = \frac{x^2}{y}$. Use a differential (i.e. total derivative) to estimate the percent error in z if x is off by no more than 3% and y is off by no more than 1%.

$$z = x^2y^{-1} \text{ so } dz = 2xy^{-1} dx + (-1)x^2y^{-2} dy \text{ so } \frac{dz}{z} = \frac{2xy^{-1} dx + (-1)x^2y^{-2} dy}{x^2y^{-1}} = \frac{2xy^{-1} dx}{x^2y^{-1}} + \frac{(-1)x^2y^{-2} dy}{x^2y^{-1}} = 2\frac{dx}{x} - \frac{(-1)x^2y^{-2} dy}{x^2y^{-2}} = 2\frac{dx}{x} - \frac{$$

- $\frac{dy}{y}$. If we interpret dx, dy, dz as the difference between actual and measured values and x, y, z as actual values, then $\frac{dx}{x} \left| \frac{dz}{z} \right| = \left| 2\frac{dx}{x} \frac{dy}{y} \right| \le 2\left| \frac{dx}{x} \right| + \left| \frac{dy}{y} \right| \le 2 \cdot 3\% + 1\% = \boxed{7\%}$
- **6.** (8 points) Suppose we have a function of two variables: f(x,y). For each question circle **YES** or **NO**. Then briefly explain your answer (in a sentence or two).
- (a) Is it possible to have $f_{xy} \neq f_{yx}$? YES / NO

Clairaut's theorem says that $f_{xy} = f_{yx}$ if the mixed partials are continuous. We can in fact have $f_{xy} \neq f_{yx}$ if these mixed partials fail to be continuous.

- (b) Suppose f_x and f_y exist everywhere. Can I conclude that f is differentiable? YES / NO Differentiability is strictly stronger than the existence of partials. What is true is that if f is differentiable, then the partials exist and if the partials exist and are *continuous*, then f must be differentiable.
- 7. (12 points) Let $f(x,y) = x^3 xy + y + 1$.
- (a) Find the gradient of f and the Hessian matrix of f. $\nabla f = \langle 3x^2 y, -x + 1 \rangle$ and $H_f = \begin{bmatrix} 6x & -1 \\ -1 & 0 \end{bmatrix}$
- (b) Find the quadratic approximation of f at (x,y) = (1,2). $Q(x,y) = f(1,2) + \nabla f(1,2) \cdot \langle x-1,y-2 \rangle + \frac{1}{2}[x-1 \ y-2]H_f(1,2) \begin{bmatrix} x-1 \\ y-2 \end{bmatrix}$ $= (1-2+2+1) + \langle 3(1^2)-2,-1+1 \rangle \cdot \langle x-1,y-2 \rangle + \frac{1}{2}[x-1 \ y-2] \begin{bmatrix} 6(1) & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x-1 \\ y-2 \end{bmatrix}$ $= 2 + \langle 1,0 \rangle \cdot \langle x-1,y-2 \rangle + \frac{1}{2}[x-1 \ y-2] \begin{bmatrix} 6 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x-1 \\ y-2 \end{bmatrix}$ $= 2 + (x-1) + \frac{1}{2}6(x-1)^2 + \frac{1}{2}(-1)(x-1)(y-2) + \frac{1}{2}(-1)(x-1)(y-2)$
- (c) Find an classify the critical point(s) of f(x, y). [Use the "2nd-derivative" test to determine if critical points are relative max's, min's or saddle points.]

 $\nabla f(x,y) = \langle 0,0 \rangle$ thus $3x^2 - y = 0$ and -x + 1 = 0 so that x = 1 and so $y = 3(1^2) = 3$. Therefore, f has only 1 critical point: (x,y) = (1,3). At this point, $H_f(1,3) = \begin{bmatrix} 6 & -1 \\ -1 & 0 \end{bmatrix} \stackrel{\text{det}}{\Longrightarrow} 6(0) - (-1)(-1) = -1 < 0$. Therefore, (1,3) is a saddle point.

- **8.** (10 points) Let $f(x,y) = y^3 + x^2y + 3x + 4$
- (a) Find the directional derivative of f at the point (x,y)=(1,0) and in the same direction as $\mathbf{v}=\langle -3,4\rangle$.

We need to normalize \mathbf{v} to find the corresponding unit vector to plug into the directional derivative. $\mathbf{u} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{1}{\sqrt{(-3)^2 + 4^2}} \langle -3, 4 \rangle = \left\langle -\frac{3}{5}, \frac{4}{5} \right\rangle$. Next, $\nabla f = \langle 2xy + 3, 3y^2 + x^2 \rangle$ so that $\nabla f(1,0) = \langle 2(1)0 + 3, 3(0^2) + 1^2 \rangle = \langle 3, 1 \rangle$. Therefore, $D_{\mathbf{u}}f(1,0) = \nabla f(1,0) \bullet \mathbf{u} = \langle 3, 1 \rangle \bullet \left\langle -\frac{3}{5}, \frac{4}{5} \right\rangle = -\frac{9}{5} + \frac{4}{5} = \boxed{-1}$.

(b) Can the directional derivative of f at the point (x, y) = (1, 0) be equal to 2? YES / NOCan it be equal to -10? YES / NO

Notice that $|\nabla f(1,0)| = |\langle 3,1 \rangle| = \sqrt{10}$. Therefore, the directional derivative at the point (1,0) takes on a maximum value of $\sqrt{10}$ (in the gradient direction) and a minimum value of $-\sqrt{10}$ (in the negative gradient direction). Therefore, the directional derivative at (x,y)=(1,0) is equal to 2 for some (unit) direction vector (since $-\sqrt{10} \le 2 \le \sqrt{10}$), but it cannot be -10 (since $-10 < -\sqrt{10} = \min$).

- **9.** (10 points) Suppose f(x,y) is a "nice" function (with continuous partials of all orders).
- (a) $Q(x,y) = 2(x-1) + 3(y-2) + (x-1)^2 + 3(x-1)(y-2) + 3(y-2)^2$ is the quadratic approx. at (x,y) = (1,2).

$$\nabla f(1,2) = \langle 2,3 \rangle$$
 $H_f(1,2) = \begin{bmatrix} 2 & 3 \\ 3 & 6 \end{bmatrix}$

Be careful! While $Q(x,y) = \cdots + f_x(1,2)(x-1) + \cdots$ so that $f_x(1,2) = 2$ (and likewise $f_y(1,2)$. The quadratic terms are a bit trickier. For example: $Q(x,y) = \cdots + \frac{1}{2}f_{yy}(1,2)(y-2)^2 + \cdots$ so $3 = \frac{1}{2}f_{yy}(1,2)$ and so $f_{yy}(1,2) = 6$. But $Q(x,y) = \cdots + \frac{1}{2}f_{xy}(1,2)(x-1)(y-2) + \frac{1}{2}f_{yx}(1,2)(x-1)(y-2) + \cdots$ with $f_{xy} = f_{yx}$ (we assumed continuous partials of all orders). Thus $f_{xy}(1,2) = \frac{1}{2}f_{xy}(1,2) + \frac{1}{2}f_{yx}(1,2) = 3$ so the off diagonals are 3 (not $3 \cdot 2 = 6$).

Is
$$(x,y) = (1,2)$$
 a critical point of $f(x,y)$? YES /

If not, why not? If so, what kind (relative min, relative max, saddle point or not enough information)?

This is not a critical points since $\nabla f(1,2) \neq \langle 0,0 \rangle$.

(b) $Q(x,y) = 5 + (-3)(x-3)^2 + 2(x-3)(y+2) + (-3)(y+2)^2$ is the quadratic approx. at (x,y) = (3,-2).

$$\nabla f(3,-2) = \langle 0,0 \rangle$$
 $H_f(3,-2) = \begin{bmatrix} -6 & 2\\ 2 & -6 \end{bmatrix}$

Is
$$(x,y) = (3,-2)$$
 a critical point of $f(x,y)$? **YES** / **NO**

If not, why not? If so, what kind (relative min, relative max, saddle point or not enough information)?

Notice that $\nabla f(3,-2) = \langle 0,0 \rangle$ so this is a critical point. $H_f(3,-2) = \begin{bmatrix} -6 & 2 \\ 2 & -6 \end{bmatrix} \xrightarrow{\text{det}} -6(-6) - 2(2) = 32 > 0$ and $f_{xx}(3,-2) = -6 < 0$. (3,-2) is a relative maximum.

10. (10 points) Set up but do not solve the equations used in the method of Lagrange multipliers for finding the minimum and maximum values of $f(x, y, z) = xy + z^3$ constrained to $x + y^2 + z^3 = 1$. Circle Your Answer!

 $\nabla f = \langle y, x, 3z^2 \rangle$ and $\nabla g = \langle 1, 2y, 3z^2 \rangle$. Our Lagrange multiplier equations are: $\nabla f = \lambda \nabla g$ and the constraint, so...

$$y = \lambda$$
 $x = 2y\lambda$ $3z^2 = 3z^2\lambda$ $x + y^2 + z^3 = 1$

Math 2130-102

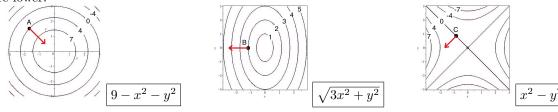
Test #2

October 16th, 2013

Name: Answer Key

Be sure to show your work!

1. (12 points) Three level curve plots are shown below. I have labeled the levels so you know which curves are higher and which are lower.



- (a) The plots above correspond to the functions: $f(x,y) = x^2 y^2$, $f(x,y) = 9 x^2 y^2$, and $f(x,y) = \sqrt{3x^2 + y^2}$. Write the correct formula below each plot.
- (b) Sketch a gradient vector at the points A, B, and C. If the vector is **0**, draw an "X" on the point. [Don't worry about having the correct length. I'm just looking for the correct direction.] [This is the same as section 101's problem #1.]

2. (8 points) State the chain rule for the derivative or partial derivative (whichever makes sense) of w with respect to t where w = f(x, y, z), x = g(t), y = h(t), and $z = \ell(t)$. Make sure you clearly label regular derivatives with d's and partials with ∂ 's. If your handwriting leaves this difficult to determine, write "regular" and "partial" and draw arrows to which is which.

When w is thought of as a function of x, y, z, we should write down partials. When w is thought of as depending directly on t (alone), we should write a regular derivative. The derivatives of x, y, and z are regular derivatives since these variables only depend on t.

 $\frac{dw}{dt} = \frac{\partial w}{\partial x}\frac{dx}{dt} + \frac{\partial w}{\partial y}\frac{dy}{dt} + \frac{\partial w}{\partial z}\frac{dz}{dt} \qquad \text{OR} \qquad w'(t) = f_x \cdot g'(t) + f_y \cdot h'(t) + f_z \cdot \ell'(t)$

3. (10 points) Show the following limit does not exist:

$$\lim_{(x,y,z)\to(0,0,0)} \frac{xy + yz + zx}{x^2 + y^2 + z^2}$$

Let's approach along the x-axis, $\mathbf{r}(t) = \langle t, 0, 0 \rangle$, we get: $\lim_{t \to 0} \frac{0 + 0 + 0}{t^2 + 0^2 + 0^2} = 0$. The other axes will yield the same result.

However, when we approach along the diagonal line $\mathbf{r}(t) = \langle t, t, t \rangle$, we get: $\lim_{t \to 0} \frac{t^2 + t^2 + t^2}{t^2 + t^2 + t^2} = \lim_{t \to 0} \frac{3t^2}{3t^2} = 1$. Since $0 \neq 1$, this limit cannot exist (if this limit existed we would get the same answer no matter how we approached the origin). Note: Where did my choice $\mathbf{r}(t) = \langle t, t, t \rangle$ come from? Well, I looked for a way to "unify" the denominator (i.e. $x^2 = y^2 = z^2$). This sort of choice usually yields something interesting.

4. (10 points) Suppose that $z = xy^3$. I measured and found that x = 2 and y = 1, but I think my measurement for x might be off by ± 0.2 and my measurement for y might be off by ± 0.1 . Use a differential (i.e. total derivative) to estimate the possible error in z.

First, $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = y^3 dx + 3xy^2 dy$. We interpret dx, dy, dz as the difference between actual and measured values. We've been told that dx is at most 0.2 and dy is at most 0.1. Thus $dz = 1^3(0.1) + 3(2)(1^2)(0.1) = 0.2 + 0.6 = \boxed{0.8}$.

5. (10 points) Find an equation for the plane tangent to $xe^{xyz} + y^2z = -1$ at the point (x, y, z) = (0, 1, -1).

Here we have a level surface with $F(x, y, z) = xe^{xyz} + y^2z$ and F(x, y, z) = -1. Note that $F(0, 1, -1) = 0e^{0(1)(-1)} + 1^2(-1) = -1$ as needed.

$$\nabla F = \langle e^{xyz} + xe^{xyz}yz, xe^{xyz}xz + 2yz, xe^{xyz}xy + y^2 \rangle$$

$$\nabla F(0, 1, -1) = \langle e^{0(1)(-1)} + 0e^{0(1)(-1)}(1)(-1), 0e^{0(1)(-1)}0(-1) + 2(1)(-1), 0e^{0(1)(-1)}(0)1 + 1^2 \rangle$$

$$= \langle e^0 + 0, 0 - 2, 0 + 1 \rangle = \langle 1, -2, 1 \rangle$$

$$1(x - 0) - 2(y - 1) + 1(z - (-1)) = 0 \implies x - 2y + z + 3 = 0$$

- 6. (8 points) Same as Section 101's problem #6.
- 7. (12 points) Let $f(x,y) = x^3 + xy + y 8$.
- (a) Find the gradient of f and the Hessian matrix of f. $\nabla f = \langle 3x^2 + y, x + 1 \rangle$ and $H_f = \begin{bmatrix} 6x & 1 \\ 1 & 0 \end{bmatrix}$
- (b) Find the quadratic approximation of f at (x, y) = (2, 1).

$$\begin{split} Q(x,y) &= f(2,1) + \nabla f(2,1) \bullet \langle x-2,y-1 \rangle + \frac{1}{2}[x-2\ y-1] H_f(2,1) \begin{bmatrix} x-2 \\ y-1 \end{bmatrix} \\ &= (8+2+1-8) + \langle 3(2^2)+1,2+1 \rangle \bullet \langle x-2,y-1 \rangle + \frac{1}{2}[x-2\ y-1] \begin{bmatrix} 6(2) & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x-2 \\ y-1 \end{bmatrix} \\ &= 3 + \langle 13,3 \rangle \bullet \langle x-2,y-1 \rangle + \frac{1}{2}[x-2 & y-1] \begin{bmatrix} 12 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x-2 \\ y-1 \end{bmatrix} \\ &= 3 + 13(x-2) + 3(y-1) + \frac{1}{2}12(x-2)^2 + \frac{1}{2}(1)(x-2)(y-1) + \frac{1}{2}(1)(x-2)(y-1) \end{split}$$

(c) Find an classify the critical point(s) of f(x, y). [Use the "2nd-derivative" test to determine if critical points are relative max's, min's or saddle points.]

 $\nabla f(x,y) = \langle 0,0 \rangle$ thus $3x^2 + y = 0$ and x + 1 = 0 so that x = -1 and so $y = -3(-1)^2 = -3$. Therefore, f has only 1 critical point: (x,y) = (-1,-3). At this point, $H_f(-1,-3) = \begin{bmatrix} -6 & 1 \\ 1 & 0 \end{bmatrix} \stackrel{\text{det}}{\Longrightarrow} -6(0) - 1(1) = -1 < 0$. Therefore, (-1,-3) is a saddle point.

8. (10 points) Let $f(x,y) = xy^3 + 3y + 55$

(a) Find the directional derivative of f at the point (x,y)=(0,1) and in the same direction as $\mathbf{v}=\langle 4,-3\rangle$.

We need to normalize \mathbf{v} to find the corresponding unit vector to plug into the directional derivative. $\mathbf{u} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{1}{\sqrt{4^2 + (-3)^2}} \langle 4, -3 \rangle = \left\langle \frac{4}{5}, -\frac{3}{5} \right\rangle$. Next, $\nabla f = \langle y^3, 3xy^2 + 3 \rangle$ so that $\nabla f(0, 1) = \langle 1^3, 3(0)1^2 + 3 \rangle = \langle 1, 3 \rangle$. Therefore,

 $D_{\mathbf{u}}f(0,1) = \nabla f(0,1) \bullet \mathbf{u} = \langle 1, 3 \rangle \bullet \left\langle \frac{4}{5}, -\frac{3}{5} \right\rangle = \frac{4}{5} - \frac{9}{5} = \boxed{-1}.$

(b) Can the directional derivative of f at the point (x,y) = (1,0) be equal to 10? YES / NO

Can it be equal to -1? YES / NO

Notice that $|\nabla f(0,1)| = |\langle 1,3 \rangle| = \sqrt{10}$. Therefore, the directional derivative at the point (0,1) takes on a maximum value of $\sqrt{10}$ (in the gradient direction) and a minimum value of $-\sqrt{10}$ (in the negative gradient direction). Therefore, the directional derivative at (x,y) = (0,1) is equal to -1 for some (unit) direction vector (since $-\sqrt{10} \le -1 \le \sqrt{10}$), but it cannot be 10 (since $10 > \sqrt{10} = \text{maximum}$).

9. (10 points) Suppose f(x,y) is a "nice" function (with continuous partials of all orders).

(a) $Q(x,y) = 2 + 5(x-3)^2 + 2(x-3)(y+2) + 3(y+2)^2$ is the quadratic approx. at (x,y) = (3,-2).

$$\nabla f(3, -2) = \left\langle 0, 0 \right\rangle \qquad H_f(3, -2) = \begin{bmatrix} 10 & 2 \\ 2 & 6 \end{bmatrix}$$

See section 101's problem #9(a)'s note.

Is (x, y) = (3, -2) a critical point of f(x, y)? **YES** / **NO**

If not, why not? If so, what kind (relative min, relative max, saddle point or not enough information)?

Notice that $\nabla f(3,-2) = \langle 0,0 \rangle$ so this is a critical point. Next, $H_f(3,-2) = \begin{bmatrix} 10 & 2 \\ 2 & 6 \end{bmatrix} \stackrel{\text{det}}{\Longrightarrow} 10(6) - 2(2) = 56 > 0$ and $f_{xx}(3,-2) = 10 > 0$. Therefore, (3,-2) is a relative minimum.

(b) $Q(x,y) = 6x - 3(y-4) + x^2 + 2x(y-4) - 3(y-4)^2$ is the quadratic approx. at (x,y) = (0,4).

$$\nabla f(0,4) = \left\langle 6, -3 \right\rangle \qquad H_f(0,4) = \begin{bmatrix} 2 & 2 \\ 2 & -6 \end{bmatrix}$$

Is (x,y) = (0,4) a critical point of f(x,y)? YES /

If not, why not? If so, what kind (relative min, relative max, saddle point or not enough information)?

This is not a critical point since $\nabla f(0,4) \neq \langle 0,0 \rangle$.

10. (10 points) Use the method of Lagrange multipliers to find the minimum and maximum values of f(x,y) = 2x + 4y constrained to $x^2 + y^2 = 5$.

We need our Lagrange multiplier equations. Notice that $\nabla f = \langle 2, 4 \rangle$ and $\nabla g = \langle 2x, 2y \rangle$ (if we set $g(x,y) = x^2 + y^2$). Therefore, $\nabla f = \lambda \nabla g$ and our constraint equation give us $2 = 2x\lambda$, $4 = 2y\lambda$, and $x^2 + y^2 = 5$. We can symmetrize (i.e. multiply the first equation by y and the second by x to make the right hand sides match). Thus $2y = 2xy\lambda = 4x$. Thus y = 2x. Plugging this into the constraint yields $x^2 + (2x)^2 = 5$ so that $5x^2 = 5$ and so $x^2 = 1$. Therefore, $x = \pm 1$. But y = 2x so then y = 2 if x = 1 and y = -2 if x = -1.

Finally, we should plug these points into our objective function to determine the extreme values: f(1,2) = 2(1) + 4(2) = 10 and f(-1,-2) = 2(-1) + 4(-2) = -10. Therefore, if f is constrained to $x^2 + y^2 = 5$, its maximum value is 10 and its minimum value is -10.